

# WEST Search History





DATE: Monday, August 06, 2007

Hide?	<u>Set</u> <u>Name</u>	<u>Query</u>	<u>Hit</u> <u>Count</u>
	<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>		
<input type="checkbox"/>	L46	robot and L45	5
<input type="checkbox"/>	L45	control and "gain phase compensation" and "servo controller"	5
<input type="checkbox"/>	L44	L43 and L28	422
<input type="checkbox"/>	L43	(700/245   700/247   700/249   700/250   700/252   700/253   700/258   700/260   700/264 or 318/568.1   318/568.11   318/568.12   318/568.16   318/568.17   318/568.22   318/.568.25 or 901/1   901/2   901/9 or 180/8.1   180/8.6).cccls.	6926
<input type="checkbox"/>	L42	floor and L41	13
<input type="checkbox"/>	L41	force\$ and L40	13
<input type="checkbox"/>	L40	control\$4 and L39	13
<input type="checkbox"/>	L39	actuator and L38	13
<input type="checkbox"/>	L38	value and L37	14
<input type="checkbox"/>	L37	joint\$ and L36	14
<input type="checkbox"/>	L36	stairs and L35	17
<input type="checkbox"/>	L35	L30 and difference and floor	96
<input type="checkbox"/>	L34	L32 and L30	0
<input type="checkbox"/>	L33	second yoke and (L32 or L31)	1
<input type="checkbox"/>	L32	(5746771   5280783   4329982   4834073   6077203   6203511   4782827   5239987   5399147   6042520   4825852   4803975   4784663   5735905   5755807   4770661   4795471   5928175   6120510   3925824   3863273   3795922   4172296   4123806   4266302   4279042   4285071   4287617   4338926   4417571   4487203   4520512   4520511   4524766   4530114   4532660   4536894   4551863   4567885   4614518   4621629   4762122   4770659   4798610   4815454   4822368   4828565   4834081   4846840   4904265).pn.	105
<input type="checkbox"/>	L31	legged robot	321
<input type="checkbox"/>	L30	reaction force and correction and calculat\$4 and leg\$4 and robot\$6	144
<input type="checkbox"/>	L29	10/476153	4
<input type="checkbox"/>	L28	robot\$6 and (walk\$3 or biped or humanoid or two legged) and (inlina\$6 or betn or tilt or deviat\$5 or obliqu\$5 or indirect\$4 or change direction or slope or slant)	4929
<input type="checkbox"/>	L27	('6711469'   '6697709'   '6567724'   '6505098'   '6493606'   '6480761'   '6330494'   '6289265'   '6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	16
<input type="checkbox"/>	L26	marc.xa. and legged and inclination	26
<input type="checkbox"/>	L25	marc.xa. and legged and inclinaiton	0
<input type="checkbox"/>	L24	('5404086')!.ABPN1,NRPN,PN,TBAN,WKU.	2
<input type="checkbox"/>	L23	(edditng or updating) and (motion or traject\$4 or movement) and zmp and robot\$6	16

<input type="checkbox"/>	L22	(edditng or updating) same (motion or traject\$4 or movement) and zmp and robot\$6	8
<input type="checkbox"/>	L21	(edditng or updating) same (motion or traject\$4 or movement) and L20	7
<input type="checkbox"/>	L20	robot and zmp and yaw	128
<input type="checkbox"/>	L19	marc.xa. and zmp	33
<input type="checkbox"/>	L18	10/181500	3
<input type="checkbox"/>	L17	('6697709'  '6289265'  '6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	6
<input type="checkbox"/>	L16	marc.xa. and robot and zmp	33
<input type="checkbox"/>	L15	(motions or movement or displacement) and L14	91
<input type="checkbox"/>	L14	computer and L13	102
<input type="checkbox"/>	L13	record\$3 and L12	102
<input type="checkbox"/>	L12	(request or command) and L11	122
<input type="checkbox"/>	L11	L7 and L10	127
<input type="checkbox"/>	L10	execut\$5 and L9	242486
<input type="checkbox"/>	L9	run or L7	1209830
<input type="checkbox"/>	L8	(6458772 or 6284156 or 6348461 or 6262044 or 6410586 or 6342245 or 6277877 or 6399557 or 3857856 or 5835892 or 6376445 or 6440911 or 6163111 or 5610305 or 5230889 or 4391489 or 4483594 or 6410749 or 4876009 or 6358945 or 6281227 or 6391397 or 6432994 or 4920120 or 5874378 or 6374641 or 5384779 or 5523998 or 5537098 or 4260406 or 4293439 or 4386503 or 5179438 or 5208607 or 6275216 or 5534261 or 5640119 or 5831440 or 6049212 or 6271251 or 4949326 or 5015815 or 5194938 or 4870247 or 6258470 or 6316465 or 6388989 or 4505827 or 5210848 or 5230070).pn.	99
<input type="checkbox"/>	L7	(similar or "same") function and L6	149
<input type="checkbox"/>	L6	robot and control software and (chang\$3 or replac\$5)	1716
<input type="checkbox"/>	L5	('20050125099')!.ABPN1,NRPN,PN,TBAN,WKU.	2
<input type="checkbox"/>	L4	(10/126774   10/970977   10/935607   10/919172   10/775845   10/732446   10/726597   10/683496   10/637890)	17
<input type="checkbox"/>	L3	(motion or displacement or trajector\$3) and L2	97
<input type="checkbox"/>	L2	(humanoid or two legged robot and human like robot) and zmp and comput\$5	100
<input type="checkbox"/>	L1	10/726597	1

END OF SEARCH HISTORY